Abstract—Dynamic and static current injection methods to improve the linearity of a current commutating mixer are investigated and a double-balanced CMOS mixer (DBM) providing high linearity is presented in this paper. A cross-coupled pair is used in the IF stage of the mixer to dynamically inject current into the mixer to provide a high linearity. The proposed DBM was fabricated using a standard 130-nm CMOS process and was tested on-wafer. The double-balanced mixer delivers 10-dB conversion gain, 9.5-dBm third-order intercept point, and input $P_{1\text{d}B}$ of $-2.4$ dBm. RF bandwidth of the proposed mixer is 6 GHz, covering 0.5–6.5 GHz with an IF bandwidth of 300 MHz. RF to IF and LO to IF isolation are also better than 59 dB in the whole frequency band. The circuit uses an area of 0.015 mm$^2$ excluding bonding pads and draws 4.5 mW from a 1.2 V supply.

Index Terms—CMOS active mixer, cross-coupled current injection, current commutating mixer, dynamic current injection, high linearity, RF integrated circuits.

I. INTRODUCTION

In submicrometer CMOS nodes with reduced power consumption, it is challenging to design active mixers with acceptable linearity, conversion gain, and noise figure (NF). Different methods have been used to overcome the tradeoff between conversion gain, NF, power consumption, and linearity measures [$P_{1\text{d}B}$ and third-order intercept point (IIP3)] of the mixer, improving the linearity while the other metrics do not change drastically.

Harmonic distortion cancelation methods are one of the main approaches to improve linearity. In feed-forward techniques, such as the derivative superposition method [1], the third-order intermodulation product of the mixer is canceled through the use of two intermodulation terms with equal amplitude and opposite phase. Noise contribution of the additional circuitry and the dependence of the linearity improvement to the accuracy and the variation of the required phase shift are the common challenges with this technique. Injecting the intermodulation products to the mixer [2] is another method which improves the overall performance of the mixer while, in return, the mixer consumes more power and becomes larger due to the use of inductors.

The other approach aims to reduce the severity of the above-mentioned tradeoff. This is usually implemented by providing independent bias currents for the transconductance and the switching stages [3], current bleeding [4], [5], injecting current into mixer and reducing the current in switching devices and loads [6]–[8], or current reuse and folded-switching [9]–[12] which take the advantage of pMOS–nMOS pairs to improve gain and linearity both in transconductance and IF stages. However, degraded gain performance in high frequencies, higher power consumption, and occupying larger area, are among the common designs’ drawbacks.

In this paper, a novel dynamic current injection method is proposed to improve the linearity and conversion gain of the mixer. Unlike other current injection methods, in the proposed mixer, the current injection is confined to the IF stage to avoid the use of inductor and increase in the power consumption. A cross-coupled pMOS pair, derived with the LO signal, is used to dynamically inject current into the mixer, avoiding gain compression in the output nodes. This paper is an extended version of [13]. Here, static and dynamic current injection methods are studied further. Also, the design procedure of the proposed dynamically current injected mixer is provided.

II. CURRENT INJECTION CONCEPT

The IIP3 in an active commutating mixer is mostly determined by the overdrive voltage of the transconductance stage. Increasing the overdrive voltage of this stage, to achieve a better mixer linearity, leads to lower voltage headroom in the IF stage and consequently lower conversion gain. Higher load resistors and active loads [11] could be used to provide higher conversion gain, but both methods lead to linearity degradation due to the signal compression at the mixer’s output. Use of external current sources in IF stage, as shown in Fig. 1, to provide part of the commutating current lets the designer improve the linearity further.

The static and dynamic current injection methods have been investigated and used widely [6]–[8] to inject current into the node P, improving linearity and flicker NF, respectively, while maintaining high conversion gain. However, the capacitive loading of the node P degrades conversion gain and consequently the NF of the mixer at high frequencies. In the method
proposed here, the current injection is implemented at the IF stage of the mixer to ensure minimum capacitive loading of the mixer at the node P.

The design process of the proposed mixer is based on improving the signal compression at the output while improving the conversion gain. Current injection leads to conversion gain, noise, and linearity metrics that could not be achieved together in conventional current commutating mixer.

In a basic single-balanced mixer (SBM) and the absence of the injected current, \( I_{\text{inj}} = 0 \), in Fig. 1, the output nodes voltages, \( V_X \) and \( V_Y \), need to remain high enough to maintain \( M_1 \) in saturation and avoid \( M_2 \) and \( M_3 \) entering into the triode region when they are both turned ON and carrying current. The amplitude of the LO signal that places either \( M_2 \) or \( M_3 \), as a differential pair, at the edge of conduction is \( \sqrt{2} V_{\text{ov2,3}} \). \( V_{\text{ov2,3}} \) is the overdrive voltages of \( M_2 \) and \( M_3 \) when \( V_{L0} = 0 \). Therefore, the minimum voltage of the output nodes, \( V_{X,Y_{\text{min}}} \), is

\[
V_{X,Y_{\text{min}}} = V_{\text{ov1}} + \left(1 + \frac{\sqrt{2}}{2}\right) V_{\text{ov2,3}} \tag{1}
\]

where \( V_{\text{ov1}} \) is the overdrive voltages of the transconductor stage. In Fig. 1, the transconductance stage is biased by \( V_B \) while \( V_{rf} \) denotes the input RF signal. The bias voltage and the LO signal of the switching stage are indicated by \( V_{CM} \) and \( V_{LO} \), respectively. The maximum voltage drop across load resistors, \( V_{R_{\text{max}}} \), maximum load resistance, \( R_{L0} \), and maximum voltage conversion gain, \( CG_0 \), of the mixer are given by

\[
V_{R_{\text{max}}} = \text{Max}(V_{R_{1,2}}) = V_{DD} - V_{X,Y_{\text{min}}} \tag{2}
\]
\[
R_{L0} = R_L | I_{\text{inj}} = 0 = \frac{V_{R_{\text{max}}}}{I_1} \tag{3}
\]
\[
CG_0 = \frac{2 V_{R_{\text{max}}}}{V_{\text{ov1}}} \tag{4}
\]

Based on (1) and (2), smaller \( V_{\text{ov1}} \) and \( V_{\text{ov2,3}} \) should be used to improve the voltage conversion gain of the mixer determined by (4). However, smaller \( V_{\text{ov1}} \) degrades IIP3. Therefore, the mixer’s current and overdrive voltages give little room for improving gain and linearity simultaneously. Increasing \( R_L \) beyond \( R_{L0} \) in (3) results in pushing \( V_X \) and \( V_Y \) lower than \( V_{X,Y_{\text{min}}} \). Therefore, either \( M_2 \) or \( M_3 \) enters triode region before the other one turns OFF. This degrades the mixer’s linearity in the output. Providing a part of the switching stage’s current, through external current sources, keeps \( V_Y \) and \( V_X \) higher than the limit determined in (1). Consequently, the mixer avoids signal compression in the output and achieves higher linearity with higher \( R_L \) and conversion gain than \( R_{L0} \) and \( CG_0 \), respectively.

A. Static Current Injection Method

Considering a constant injection current of \( I_{\text{inj}} = m_s I_1 \), the current through \( R_L \) decreases to \( (1-m_s)I_1 \) when either \( M_2 \) or \( M_3 \) is turned OFF. \( m_s \) is the static current injection ratio. The maximum load resistor, \( R_{L_{\text{static}}} \), and the maximum conversion gain, \( CG_{\text{static}} \), in this case, are

\[
R_{L_{\text{static}}} = R_L | I_{\text{inj}} = m_s I_1 = \frac{1}{1-m_s} R_{L0} \tag{5}
\]
\[
CG_{\text{static}} = \frac{2 V_{R_{\text{max}}}}{1-m_s} \frac{V_{\text{ov1}}}{\pi} = \frac{1}{1-m_s} CG_0. \tag{6}
\]

Although the maximum voltage drop across \( R_L \) is equal to (2), at LO zero-crossing points, the current splits equally between \( M_2 \) and \( M_3 \). This causes \( V_{R1} \) and \( V_{R2} \) to drop as well. Therefore, at LO zero crossings

\[
V_{R1} = V_{R2} = R_{L_{\text{static}}} \left(\frac{I_1}{2} - m_s I_1\right). \tag{7}
\]

Static injection current sources can be implemented as shown in Fig. 2 and with a pair of pMOS devices, \( M_4 \) and \( M_5 \). The overdrive voltage of \( M_4 \) and \( M_5 \), \( V_{\text{ov4,5}} \), is fixed by their gates bias voltage, \( V_{\text{ING}} \). To maintain \( M_4 \) and \( M_5 \) in saturation at LO zero crossings, \( V_{R1} \) and \( V_{R2} \) should remain higher than \( V_{\text{ov4,5}} \). Therefore, using (7), the maximum current injection ratio, \( m_{s_{\text{max}}} \), is determined by

\[
m_{s_{\text{max}}} = \frac{V_{\text{max}} - V_{\text{ov4,5}}}{V_{\text{ov4,5}} - V_{\text{ov4,5}}}. \tag{8}
\]

\( m_{s_{\text{max}}} \) is always less than 0.5 in (8) and reaches its maximum for very low \( V_{\text{ov4,5}} \). Therefore, in static current injection method, the signal compression at the output can be overcome for a limited improvement in conversion gain.
Based on (6), signal compression due to only 5.2 dB of gain improvement with $V_{ov\text{inj}} = 0.05$ V and $V_{\text{Rmax}} = 0.65$ V can be achieved.

B. Dynamic Current Injection Method

Fig. 3(a) shows the dynamic current injection concept in one branch of the mixer. $I_{\text{inj}}$ and $I_2$ are represented by the dashed and solid lines, respectively. In positive half cycle of the LO signal, the injection current is a fraction of the current through $M_2$

$$I_{\text{inj}}(t) = m_{\text{ins}} \cdot I_2(t). \quad (9)$$

Equation (9) shows the injection current at each instant is a constant fraction of the instantaneous current through the switches instead of the overall mixer’s current, $I_1$. $I_{\text{inj}}$ is $(1/2)m_{\text{ins}}I_1$ at LO zero crossings and reaches its maximum of $m_{\text{ins}}I_1$ determined by (9) in each period of the LO signal and when $M_3$ turns OFF. For dynamic current injection, the load resistor, $R_L^{-}\text{dynamic}$, and the conversion gain, $CG^{-}\text{dynamic}$, are determined by

$$R_L^{-}\text{dynamic} = R_L | I_{\text{inj}}(t) = m_{\text{ins}}I_2(t) = \frac{1}{1 - m_{\text{ins}}} R_L \quad (10)$$

$$CG^{-}\text{dynamic} = \frac{1}{1 - m_{\text{ins}}} CG_0. \quad (11)$$

In comparison to the static current injection, the first immediate advantage of this method is the elimination of voltage drop across the load resistor at the zero-crossing instances of the LO signal

$$V_R(t) = (1 - m_{\text{ins}}) \cdot I_2(t) \quad R_L^{-}\text{dynamic} = I_2(t) \cdot R_L. \quad (12)$$

As shown in (12), $V_R(t)$ for the dynamic current injection of Fig. 3 is independent of $m_{\text{ins}}$ and equal to $V_R(t)$ for the simple mixer with $R_L$ as the load resistance. Therefore, increasing $m_{\text{ins}}$ higher than 0.5, which is the asymptotic limit for the static current injection method becomes possible. Increasing $m_{\text{ins}}$ increases the voltage conversion gain while based on (12), the output voltages remain intact. This leads to the independence of the mixer’s gain and linearity performance in ideal dynamic current injection. Unlike the static current injection ratio which is constant in the whole LO signal’s period, the dynamic current injection ratio, $m_2(t)$, given by

$$m_2(t) = \frac{I_{\text{inj}}(t)}{I_1} = m_{\text{ins}} \cdot \frac{I_2(t)}{I_1} \quad (13)$$

is periodic. Assuming piecewise linear devices, $m_{\text{ins}}$ and $m_2(t)$ are both shown in Fig. 3(b) versus a half period of the LO signal. $V_{LO}$ is the maximum amplitude of the LO signal, and $\Delta V$ is the minimum LO voltage imbalance required to turn OFF $M_3$ and steer the current completely to $M_2$. As mentioned in Section II, $\Delta V$ is equal to $\sqrt{2}V_{ov2,3}$ where the channel-length modulation is neglected. Since

$$I_1 = I_2(t) + I_3(t) \quad (14)$$

$m_2(t)$ is $(1/2)m_{\text{ins}}$ at LO zero crossings and increases to $m_{\text{ins}}$ when $M_3$ turns OFF. By changing $M_2$ to $M_3$ and replacing $I_2$ with $I_3$, (9)–(13) remain the same for the other half period of the LO signal.

To implement dynamic current injection, a pMOS cross-coupled pair as shown in Fig. 4, has been used. At zero-crossing instances, the overdrive voltages of $M_{4}$ and $M_{5}$ are equal, and provide $M_2$ and $M_3$ with equal injection currents. In the positive half period of the LO signal, $M_3$ starts to turn OFF, and $I_2$ increases until all of $I_1$ passes through $M_2$. While $I_2$ is rising in the positive half period of the LO signal, the overdrive voltage of $M_3$, connected to $-(V_{LO}/2)$, also increases and its current reaches $m_{\text{ins}}I_1$ when $M_3$ turns OFF and $I_2 = I_1$. This procedure repeats for $M_5$ and $M_4$ in the next half period of the LO signal.

III. IMPLEMENTATION OF DYNAMIC CURRENT INJECTION IN SINGLE-BALANCED MIXER

A. Design Procedure

When $I_{\text{inj}} = 0$, (1)–(4) determine the maximum available gain without compromising the mixer’s linearity. The instantaneous current injection ratio, required to achieve a higher conversion gain of $CG^{-}\text{dynamic}$, can be found using (11),

$$V_{OL}(t) = 0 \quad I_2(t) = m_{\text{ins}} \cdot I_1(t) \quad (15)$$

For instance, $m_{\text{ins}} = 0.25$ is enough to achieve the gain of $CG_0 = 40$ dB.
and is

\[ m_{\text{ins}} = 1 - \frac{CG_0}{CG_{\text{dynamic}}}. \]  

(15)

Using (3) and (10), \( R_L \)-dynamic necessary to deliver \( CG_{\text{dynamic}} \) is determined. To determine the size of the cross-coupled pair, the current injection is investigated at \( |V_{LO(t)}| = \Delta V \), when either \( M_2 \) or \( M_3 \) turns off. Considering a piecewise linear current, the current injection reaches \( m_{\text{ins}}I_1 \), using (9), to maintain \( V_X \) and \( V_Y \) equal to \( V_{X,Y_{\text{sim}}} \) when the other branch of the mixer is turned off. Therefore, at \( V_{LO(t)} = \Delta V \)

\[ I_2 = \frac{\mu_nC_{ox}}{2} \left( \frac{W}{L} \right) \left( 1 + \frac{\sqrt{2}}{2} \right)^2 V_{ov2}^2 \]  

(16)

\[ I_5 = \frac{\mu_pC_{ox}}{2} \left( \frac{W}{L} \right) \left( V_{ov5} + \frac{\sqrt{2}}{2} V_{ov2} \right)^2 \]  

(17)

where in (16) and (17), \( E_c \) is the critical electrical field while \( \mu_n \) and \( \mu_p \) are the electron and hole mobilities, respectively. Using (16) and (17) and since \( I_5(t) = m_{\text{ins}}I_2(t) \), the aspect ratio of \( M_5 \) is given by

\[ \left( \frac{W}{L} \right)_5 = m_{\text{ins}} \frac{\mu_n}{\mu_p} \left( \frac{V_{ovx} + \sqrt{2} V_{ov2}}{V_{ovx} + \frac{\sqrt{2}}{2} V_{ov2}} \right)^2 \times \frac{1 + \frac{V_{ovx} + \sqrt{2} V_{ov2}}{E_c L_2}}{1 + \frac{(1 + \frac{\sqrt{2}}{2} V_{ov2})}{E_c L_2}} \left( \frac{W}{L} \right)_2. \]  

(18)

Since \( I_2 \) is half of the current in (16), \( m_{\text{ins}} \) at the LO zero crossings is

\[ m_{\text{ins}|\text{zero crossings}} = 2m_{\text{ins}} \left( \frac{V_{ovx}}{V_{ovx} + \frac{\sqrt{2}}{2} V_{ov2}} \right)^2 \times \frac{V_{ovx} + \frac{\sqrt{2}}{2} V_{ov2}}{1 + \frac{V_{ovx} + \sqrt{2} V_{ov2}}{E_c L_2}}. \]  

(19)

As stated in Section II-B and shown in Fig. 3(b), \( m_{\text{ins}} \) is ideally constant in the whole period of the LO signal while the injection currents through \( M_5 \) and \( M_4 \) are varying periodically. Consequently, \( V_{ov5} \) is determined from (19) and is equal to

\[ V_{ov5} = \left( 1 + \frac{\sqrt{2}}{2} \right) V_{ov2} \times \frac{1}{1 + \frac{V_{ovx}}{E_c L_2}}. \]  

(20)

The last term in (20) demonstrates short channel effect of dynamic current injection pMOS pair. Assuming \( L_5 \) is chosen large enough, (20) can be simplified to

\[ V_{ov5} = \left( 1 + \frac{\sqrt{2}}{2} \right) V_{ov2}. \]  

(21)

As shown in Fig. 5, in \( 2\Delta T \) of each period of the LO signal, \( M_2 \) and \( M_3 \) are ON simultaneously. The noise contribution of both \( M_4 \) and \( M_5 \) appears in the output. When the mixer current is steered to \( M_2 \) or \( M_3 \), one of \( M_4 \) and \( M_5 \) turns OFF and only half of the cross-coupled pair produces noise in \( T_{LO} = 2\Delta T \), where \( T_{LO} \) is the LO signal period. The output noise contribution of the pMOS cross-coupled pair, \( \hat{V}_{o,n}^2 \), is given by

\[ \hat{V}_{o,n}^2 = \left( 1 + \frac{2\Delta T}{T_{LO}} \right) (g_{m5} R_L)^2 \hat{V}_{n,5}^2. \]  

(22)

In deriving (22), \( \hat{V}_{n,5}^2 \) and \( g_{m5} \) are assumed to be equal to \( \hat{V}_{n,4}^2 \) and \( g_{m4} \), respectively. Because the cross-coupled pair is placed in the output stage, (22) holds for both high-frequency and low-frequency (flicker) noise contribution. Noise behavior of the rest of the current commutating mixer is analyzed in [14] and is not included here.

The high-frequency input referred noise of the cross-coupled pair after simplification is

\[ \hat{V}_{in,n}^2 = \left( \frac{T_{LO} + 2\Delta T}{T_{LO} - 2\Delta T} \right) \frac{\sqrt{2} \times kT}{g_{m1}} \frac{g_{m5}}{g_{m1}}. \]  

(23)

The second term in (23) is the noise contribution of the transconductance stage of the mixer. If \( g_{m5} \) is significantly lower than \( g_{m1} \), the noise contribution of the cross-coupled pair is negligible compared with the input referred noise due to the transconductance stage.

The effect of the cross-coupled pair on flicker noise can be minimized by increasing the size of \( M_4 \) and \( M_5 \). Although the equivalent parasitic capacitance of the pair is more significant due to larger pMOS devices, it is acting as the output IF filter of the mixer and does not affect gain, linearity, or RF bandwidth.

**B. Design Example**

The mixer is designed for 0.13-\( \mu \)m CMOS technology node. The overdrive voltage of the transconductance and switching stages is 0.3 and 0.1 V, respectively, to guarantee high linearity and fast switching in the mixer. The current is limited to 2 mA from a 1.2 V supply voltage. \( V_{X,Y_{\text{sim}}} \) determined by (1) is, therefore, 0.5 V. An additional margin of 0.2 V is added to the minimum output voltage to ensure no linearity degradation in the output (\( V_{X,Y_{\text{sim}}} = 0.7 \) V). Using the design procedure in Section III-A and using (3) and (4), \( R_{LO} \) and \( CG_0 \) are 250 \( \Omega \) and 0.5 dB, respectively. Therefore, to design a dynamic current injected mixer with 12.5 dB of conversion gain, \( m_{\text{ins}} = 0.75 \) is required, using (11). Also, \( R_{L,\text{dynamic}} \) is 1 k\( \Omega \), determined by (10).

The overdrive voltage of the cross-coupled pair is found to be 0.15 V using (21) and (20) while \( (W/L)_5 = 1.19(W/L)_2 \).
determined using (18). In the calculation of the aspect ratio of the pMOS cross-coupled devices, using (18), \( \frac{\mu_n}{\mu_p} \) is estimated by low-field mobilities in 0.13-\( \mu \)m CMOS technology and is 4.6. Also, \( E_c = 1.5 \times 10^6 \) V/m.

The designed SBM is simulated and optimized using Spectre in Cadence and Global Foundries (formerly IBM) design kit, CMOS8RF, for 0.13-\( \mu \)m CMOS technology. To investigate the dynamic current injection method by itself, the transconductance stage is kept to its most basic implementation, shown in Fig. 1 and when \( I_{\text{inj}} = 0 \). The simulations have been carried out for current commutating mixers with the same power consumptions, device aspect ratios and sizes in three cases.

**Case A:** Simple current commutating mixer with same \( R_L \) as the dynamic current injection mixer.

**Case B:** Simple current commutating mixer with \( R_L \) optimized for maximum conversion gain.

**Case C:** The dynamic current injection mixer.

Case A is essentially the proposed mixer without its dynamic current injection mechanism. Comparing the same mixer with and without dynamic current injection will demonstrate the improvements in IIP3, \( P_{1dB} \), voltage conversion gain, and NF reached by the proposed method. Case B is also studied here to investigate the improvements in IIP3 and \( P_{1dB} \) when the simple mixer provides the same gain as the proposed mixer. Because the simple mixer fails to deliver the same gain, it is optimized to deliver maximum voltage conversion gain.

The values used in the simulations are given in Table I where \( R_{L_{dy}} \), \( R_{L_A} \), and \( R_{L_B} \) are the load resistors for dynamic current injection mixer, Case A, and Case B, respectively. All mixers consume 2 mA current from a 1.2 V supply voltage. To bias the switching devices and the cross-coupled pair together, \( V_{ov5} = 0.2 \) V is used in the simulations and \( \frac{W}{L} = 0.83(\frac{W}{L})_2 = (380/1 \mu m) \) is determined, using (18). Short channel effect on \( \mu_n \) and \( \mu_p \) is neglected and (18) overestimates the cross-coupled pair’s aspect ratio. Therefore, the size of the cross-coupled pair has been tuned in simulations for more accurate current injection and is \((350/1 \mu m)\).

Fig. 6 shows \( m_{\text{ins}} \) and \( m(t) \) versus instantaneous LO voltage in a half period. For small \( V_{\text{LO}} \) amplitudes, the current injection ratio is lower than the ideal case studied in Section II-B. Smaller \( m_d(t) \) results in \( V_{X,Y}(t) < V_{X,Y-\text{ideal}}(t) \), keeping the cross-coupled pair well into saturation region. \( V_{X,Y-\text{ideal}}(t) \) denotes output voltages, \( V_X \) and \( V_Y \) in the ideal dynamic current injection case. As the LO amplitude increases, \( m_d(t) \) also increases beyond its designed value.

The variation of the output voltages at each instance of the LO signal is shown in Fig. 7. \( V_X \) and \( V_Y \) reach their minimum when the other switch turns OFF. The output voltages start to increase again due to the extra current injection to the output nodes at larger LO signal amplitudes. For Cases A and B, output voltages are dropping far lower than the minimum
output voltage limit, estimated by (1). However, this limit is maintained for the proposed mixer. Therefore, compared with dynamically current injected mixer degraded linearity is expected for both Cases A and B.

Table II summarizes the simulation results of the mixers in these three cases. In Case A, $V_x$ and $V_y$ reduce dramatically below $V_{X_{\min}}$, determined to maintain the proper operation of the mixer. This results in a negative conversion gain of $-1.8$ dB. Although the conversion gain of the mixer can be improved by optimizing the load resistance of the mixer and reaches $9.4$ dB for Case B, it is still lower than the $12$ dB gain achieved in the dynamically current injected mixer.

The proposed method also results in a more linear mixer with $6.25$-dBm IIP3 compared with $-1.7$ and $0$ dBm for Cases A and B, respectively. Fig. 8 shows the DSB NF of the simulated mixers. Due to the low conversion gain in Case A, its high-frequency NF is $12.5$ dB. The NF of the proposed mixer is $10.25$ dB. This is only $1.75$ dB higher than the NF of Case B.

The double-balanced version of the proposed mixer is shown in Fig. 9, and it is the circuit that was fabricated and whose results are presented in Section IV.

### IV. DOUBLE-BALANCED MIXER IMPLEMENTATION AND MEASUREMENT RESULTS

To validate the dynamic current injection method, a double-balanced mixer with the dynamic current injection
as the single-balanced design. A microphotograph of the fabricated chip is shown in Fig. 10. The chip core occupies an area of 0.015 mm², excluding the bonding pads. The circuit consumes 4.5 mW of dc power from a 1.2 V supply.

In DBM implementation, there are two dynamic current injection connected to each output nodes. In each half cycle of the LO signal, one of the current injection devices provides the required injection current to the switching stage.

Two external passive baluns are used to generate the differential RF and LO signals. An external differential to single ended buffer is used to measure the mixer’s performance with spectrum analyzer. Fig. 11 shows the measured and simulated conversion gain of the mixer from 0.5 to 7 GHz. The dynamic current injection mixer shows a 3-dB gain bandwidth from 0.5 to 6.5 GHz. This large bandwidth was expected due to inductor-less design and limiting the modifications to the IF stage of the mixer.

Fig. 12 shows the measured and simulated results of conversion gain versus IF frequency. IF bandwidth of 300 MHz is achieved in the proposed mixer. As mentioned in Section III-B, the large pMOS cross-coupled pair acts as the IF filter and limits the IF bandwidth. The measurement results provided for the conversion gain of the mixer agree with the simulation results, with 0.5-dB degradation at 2 GHz, giving 10.2 dB. Also, the conversion gain’s maximum is 11.2 dB at 2.5 GHz.

Measured and simulated NF are shown in Fig. 13 for f_{LO} = 2 GHz. At IF frequency of 200 MHz, NF is 13 dB while the simulation result shows 12.34 dB. The measured results are provided for frequencies higher than 10 MHz due to the calibration limitation of the measurement instruments. Measured and simulated P1dB are −2.4 and −3.4 dBm, respectively, at f_{RF} = 2 GHz and P_{LO} = 4 dBm. Measurement results for the IIP3 of the mixer is shown in Fig. 14. The measured IIP3 and simulated IIP3 at this frequency are 9.52 and 10.56 dBm, respectively. Isolation of the IF to RF and LO signals is also better than 59 dB in whole frequency band.

A summary of the measured results and a comparison with other works are provided in Table III.

![Fig. 12. Measured and simulated conversion gain versus IF frequency. F_{RF} = 2 GHz and P_{LO} = 4 dBm.](image)

![Fig. 13. Measured and simulated DSB NF versus IF frequency. F_{RF} = 2 GHz, F_{LO} = F_{RF} + F_{IF}, and P_{LO} = 4 dBm.](image)
included in Table III [12]

\[
FOM = 10 \log \left( \frac{10 \cdot \left( \frac{I_{\text{IP3}} - 10}{20} \right)}{10 \cdot \frac{\text{NF}}{20} \cdot P} \right). \tag{24}
\]

In (24), the FOM reflects four of the most important metrics in any mixer: IIP3, NF, voltage conversion gain, \( G \), and power consumption, \( P \). Calculated FOM of the proposed mixer is 15.2 dB and is comparative to other mixers. Please note the size of the mixer is considerably lower than the previously reported designs.

V. CONCLUSION

A highly linear mixer with boosted gain, based on conventional Gilbert cell is demonstrated in this paper. The use of cross-coupled pair to inject dynamic current into the IF stage is the mechanism used to maintain a high linearity while improving the gain. Experimental test on fabricated prototype showed 10 dB conversion gain alongside 9.5-dBm IIP3.

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